Notes

## Problem Solving Introduction

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Introduction

Acknowledgements

• Wikipedia

- Jean-Charles Régin
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- Anne Benoit, ENS Lyon
- Roman Barták, Charles University

## Course outline

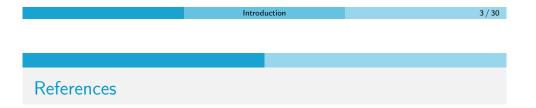
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#### Lectures

- Greedy Algorithms
- 2 Local Search
- Sconstraint Programming

## Knowledge control

- Mid-term exam
- Final exam



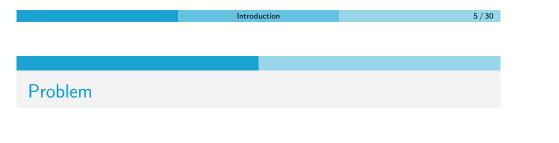
- T. Cormen, C. Leiserson, R. Rivest, Introduction à l'algorithmique, Dunod
- D. Knuth, The Art of Computer Programming
- M. Gondran et M. Minoux, Graphes et Algorithmes
- Other books as per your preference: do not hesitate to consult several

## Problem

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- A problem is a **general question**: shortest path between two points, timetable
- It is described by data and a question
- Answering this question is solving the problem
- In computer science, we seek a general answer, *i.e.*, an algorithm that works in all cases
- Instance: A specific set of data, *e.g.*, the shortest path between Nice and Nantes.



• Some problems are easy: Sorting numbers, Reversing a string

• Others are difficult: Traveling Salesman Problem (TSP)

# Traveling Salesman Problem (TSP)

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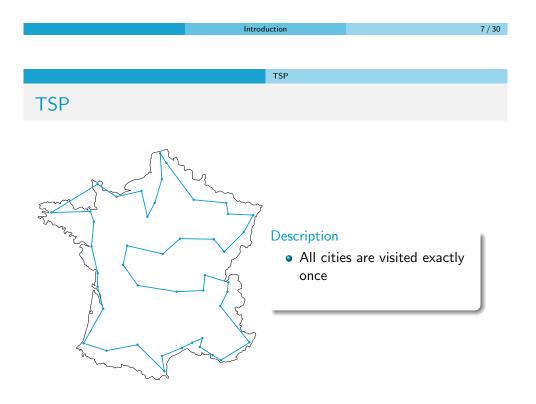
#### Description

- Data: A list of cities and pairwise distances
- Question: Find the shortest tour that visits each city exactly once

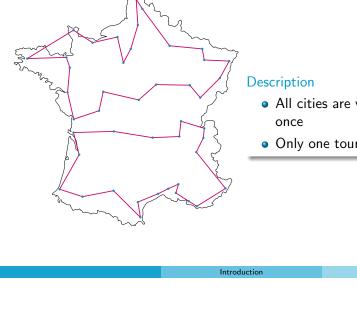
TSP

#### Mathematical Formulation

Given a complete weighted graph, find a Hamiltonian cycle of minimum weight



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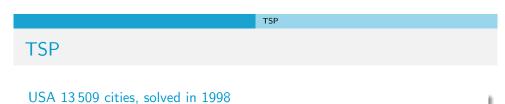
TSP

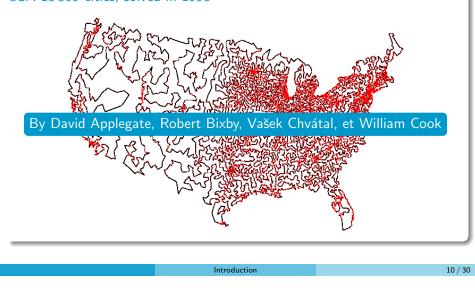
- All cities are visited exactly
- Only one tour (no sub-tours)

TSP **TSP** 

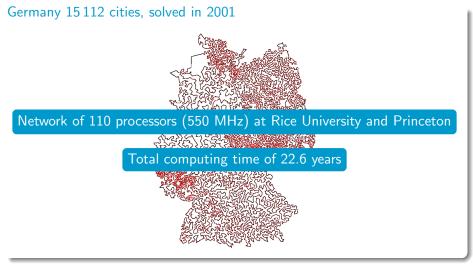
#### Description

- Some problems are equivalent to TSP
  - scheduling problems: find the order in which to build objects
- The "pure" version of TSP is rare, in practice often, we encounter variations:
  - Non-Euclidean
  - Asymmetric
- These variations do not make the problem easier
- Common applications
  - Vehicle routing (time windows, pickup and delivery, *etc.*)

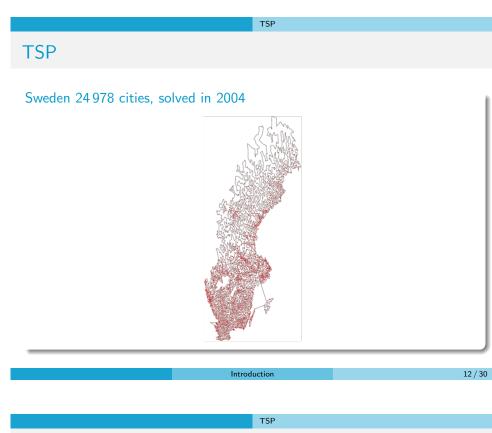














## Microchip 85 900 "cities" solved in 2006

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- Ther exist several solvers
- The most well-known solver is Concorde by William Cook (free)

TSP

- TSP solvers are typically dedicated to solving the pure problem
- TSP solvers may not handle even slight variations (asymmetric, additional constraints, *etc.*)

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	Algorithms C	Complexity	
Algorithms			

- Not all algorithms are the same, they vary in efficiency, differentiated by:
  - Computation time: slow vs fast
  - Memory usage: low vs high
- We discuss complexity in terms of time (speed) and space (memory used).

#### Algorithms Complexity

## Algorithms Complexity

Notes

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#### Purpose

- To gauge the difficulty of problems
- To estimate the computation time or space required to solve a problem
- This allows for comparing algorithms
- Expressed as a function of data size and amount

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	Algorithms	Complexity	
Problem			

Not all problems are the same, they vary according to the algorithms used to solve them

- Easy problem: we know an efficient algorithm to solve it
- Difficult problem: we do not know (yet?) an efficient algorithm to solve it
- Undecidable problem: no algorithm exists to solve it

## **NP-Completeness**

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**THE** major current issue in computer science

P vs NP

- Easy problems have polynomial algorithms
- Difficult problems have no known polynomial algorithm
- Key question: Does a polynomial algorithm always exist?

Algorithms Complexity

Introduction

## **NP-Completeness**

For some problems, we do not know if there exists polynomial algorithm, we only know exponential algorithms:  $2^n$ 

21 NP-Complete Problems by Karp

- Hitting-set: Set covering problem
- Knapsack
- Subset sum
- Bin packing
- Graph coloring
- Maximum clique

#### Remark

NP-complete problems are all equivalent and resemble each other. They can be transformed into one another

## Hitting-set: Set covering

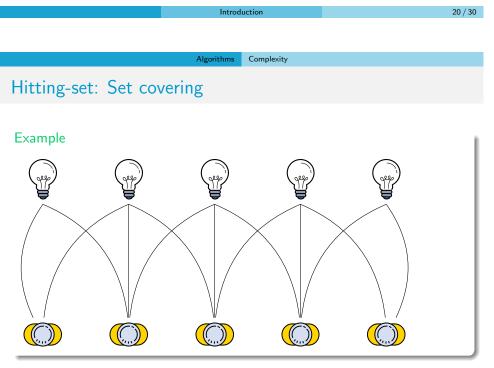
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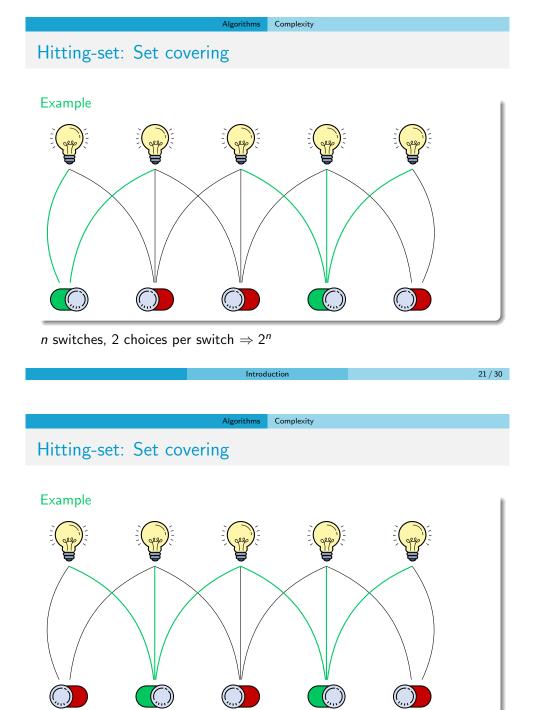
### Description

Light bulbs and switches

- A switch is connected to certain bulbs
- When a switch is pressed, all connected bulbs are lit
- **Question**: What is the minimum number of switches needed to light all bulbs?
- We want a general answer that works for all instances



*n* switches, 2 choices per switch  $\Rightarrow 2^n$ 



Introduction

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#### Algorithms Complexity

## Hitting-set: Set covering

Example

*n* switches, 2 choices per switch  $\Rightarrow 2^n$ 

Algorithms Complexity

Introduction

## Graph Vertex Coloring

#### Description

Vertices of a graph are colored such that no two adjacent vertices share the same color

### Principle of contraction and connection

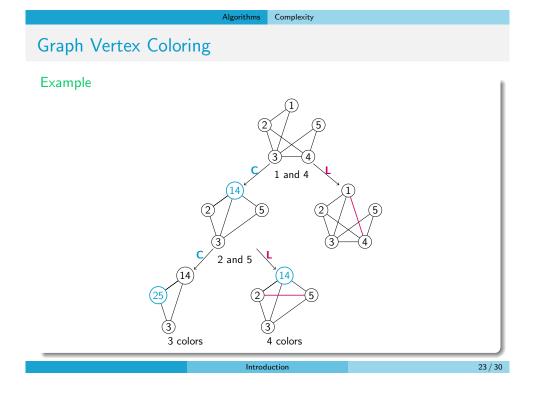
Coloring a complete graph (a clique) with n vertices requires n colors

- Given 2 non-adjacent vertices a and b
- Either they have the same color  $\Rightarrow$  Contraction (C)
- Or they have the different color  $\Rightarrow$  Connection (L)
- Reaching a clique  $\Rightarrow$  the number of vertices gives the number of colors

p possible edges, 2 choices per edge (same color or different color)  $\Rightarrow 2^p$ 

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Notes



Algorithms Complexity

## Easy vs Difficult

- Given a matrix
- For each row and each column, the number of 1's is known
- Define precisely the 0's and 1's of this matrix

#### The difference can be subtle

- Pure problem: easy
- connectivity is introduced: difficult
- Convexity is introduced: difficult
- connectivity and convexity are introduced : easy

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## **Decision Problem**

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A decision problem is a mathematically defined question about given parameters that requires a **yes or no** answer

#### Example

- Given a set of cities and a distance *d*, is there a path visiting all cities with a total length less than *d*?
- Can a graph be colored with k colors?



- An Optimization Problem involves finding the **best solution** among feasible options
- An Optimization Problems has an objective function (min or max)
- An **optimal** solution minimizes (or maximizes) the objective function among all feasible solutions

#### Example

- Shortest path visiting all the cities?
- Minimum number of colors to color a graph vertices?

## **Optimization Problem**

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### It is important to distinguish between

- An optimal solution
- Proving that a solution is optimal (optimality proof)

#### Be careful not to overgeneralize

- Finding optimality and proving it can be slow or fast
- One can be fast and not the other

Decision vs Optimization

Every optimization problem has a corresponding decision problem asking if a solution exists with a particular value

Introduction

Problems

#### Exemple

Finding the shortest path between s and t with a cost c

- Decision Problem: is there a path with cost *c*?
- Optimality proof: is there a path with cost less than c?

#### Problems

## Decision vs Optimization

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Optimization problems are often solved by solving a sequence of decision problems

- We find a feasible solution with cost k
- We ask if there is a solution with cost < k and repeat the process
- At the end, we prove optimality, because the last search does not find a solution.

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	Problems	
Hard Problems		

• We do not know if hard problems can be quickly solved

- Currently, hard problems cannot be efficiently solved (in polynomial time)
- Current solutions may be inefficient (exponential time)

Approaches Covered in the Course: how to find solutions to problems

- Using heuristics (inexact but fast)
- Complete enumeration of combinations (exact but slow)